# How to lasso positively, quickly and correctly 

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## The Lasso (a.k.a. $L_{1}$ regularization)

Consider the linear inverse problem

$$
\mathbf{y}=\mathbf{X} \boldsymbol{\beta}+\epsilon .
$$

An $L_{1}$-regularized solution takes a parameter $\delta$ and minimizes the penalized residual

$$
\|\mathbf{X} \boldsymbol{\beta}-\mathbf{y}\|_{2}^{2}+\delta\|\boldsymbol{\beta}\|_{1} .
$$

- This has the advantage that the solutions are typically sparse: used for variable selection.
- When $\delta=0$ we obtain the least squares solution. As $\delta \rightarrow \infty$, the solutions approach $\mathbf{0}$.
- We can replace $\|\boldsymbol{\beta}\|$ with a weighted version $\sum_{i} w_{i}\left|\boldsymbol{\beta}_{i}\right|$.
- Introduced into statistics by Tibshirani (1996) under the name of 'the LASSO


## Computing the Lasso

Computational challenge to efficiently compute LASSO solutions for a range of $\delta$ values (i.e. all?).

First observation (from KKT conditions): the set of LASSO solutions

$$
\operatorname{argmin}_{\boldsymbol{\beta}}\left\{\|\mathbf{X} \boldsymbol{\beta}-\mathbf{y}\|_{2}^{2}+\delta\|\boldsymbol{\beta}\|_{1}\right\}
$$

for $\delta \geq 0$ equals the set of solutions to

$$
\operatorname{argmin}_{\boldsymbol{\beta}}\left\{\|\mathbf{X} \boldsymbol{\beta}-\mathbf{y}\|_{2}^{2} \text { such that }\|\boldsymbol{\beta}\|_{1} \leq \lambda\right\}
$$

for $\lambda \geq 0$.

## LARS - Lasso algorithm

Let $\boldsymbol{\beta}(\lambda)$ denote the optimal solution for a given $\lambda$. That is,

$$
\boldsymbol{\beta}(\lambda)=\operatorname{argmin}\|\mathbf{X} \boldsymbol{\beta}-\mathbf{y}\|_{2}^{2} \text { such that }\|\boldsymbol{\beta}\|_{1} \leq \lambda .
$$

It is not too hard to show that $\boldsymbol{\beta}(\lambda)$ is piecewise linear (as a function of $\lambda$ ).


Curve starts at $\mathbf{0}$ and finishes at the un-penalised solution.

## Lasso computations

Osborne, Presnall and Turlach (2000)
394 citations
Efron, Hastie, Johnstone and Tibshirani (2004)
2909 citations

In many applications (including ours), we require variable coefficients which are non-negative.

$$
\boldsymbol{\beta}(\lambda)=\operatorname{argmin}\|\mathbf{X} \boldsymbol{\beta}-\mathbf{y}\|^{2} \text { such that } \boldsymbol{\beta} \geq \mathbf{0} \text { and }\|\boldsymbol{\beta}\| \leq \lambda .
$$

## LARS-LASSO

Efron et al. propose a 'Positive Lasso Lars' algorithm.

```
Let \boldsymbol{\beta}=\mathbf{0}\mathrm{ and c= '्}\mp@subsup{\mathbf{X}}{}{\prime}(\mathbf{y}-\mathbf{X}\boldsymbol{\beta})\mathrm{ .}
while |\mathbf{c|}>0
        \mathcal { A } = \{ i : \mathbf { c } _ { i } \text { is maximum } \} .
        Choose the search direction w
        Move }\boldsymbol{\beta}\mathrm{ in direction w
        an entry becomes negative, OR
        new variable(s) join the set of those with maximum ci
        Update c= '्}\mp@subsup{}{}{\prime}(\mathbf{y}-\mathbf{X}\boldsymbol{\beta})
end
```

Problem: can fail if more than one variable leaves or enters $\mathcal{A}$ at any one time.

## Multiple entries

Is this 'one-at-a-time' restriction a problem?
NO: you can always add random noise to break ties.
YES: With a positivity constraint ties appear as part of the algorithm (not just degenerate data). Also, we ran into problems with our degenerate models and problems.

## Our algorithm for the positive Lasso

```
Let \(\boldsymbol{\beta}=\mathbf{0}\) and \(\mathbf{c}=\mathbf{X}^{\prime} \mathbf{y}\).
while \(\|\mathbf{c}\|>0\)
    \(\mathcal{A}=\left\{i: \mathbf{c}_{i}\right.\) is maximum \(\}\).
Choose the search direction \(\mathbf{w}_{\mathcal{A}}=\left(\mathbf{X}_{\mathcal{A}}^{\prime} \mathbf{X}_{\mathcal{A}}\right)^{-1} \mathbf{1}\) Find \(\mathbf{v}\) minimizing \(\left\|\mathbf{X}_{\mathcal{A}}\left(\mathbf{v}_{\mathcal{A}}-\mathbf{w}_{\mathcal{A}}\right)\right\|_{2}\) such that
\[
\mathbf{v}_{i} \geq 0 \text { when } \boldsymbol{\beta}_{i}=0
\]
Move \(\boldsymbol{\beta}\) in direction \(\mathbf{v}\) until an entry goes negative, OR new variable(s) join the set \(\mathcal{A}\) Update \(\mathbf{c}=\mathbf{X}^{\prime}(\mathbf{y}-\mathbf{X} \boldsymbol{\beta})\). end
```


## KKT conditions

For each $\lambda$ we want to find

$$
\min _{\boldsymbol{\beta}}\|\mathbf{X} \boldsymbol{\beta}-\mathbf{y}\|_{2} \text { such that } \boldsymbol{\beta} \geq \mathbf{0} \text { and }\|\boldsymbol{\beta}\|_{1}=\lambda .
$$

From KKT conditions:
$\boldsymbol{\beta}$ solves ( $\dagger$ ) if and only if $\boldsymbol{\beta}$ is feasible and $\mathbf{c}_{i}$ is maximal for all $i$ with $\boldsymbol{\beta}_{i}>0$.

## One step

Consider moving $\boldsymbol{\beta}$ in direction v. For $\gamma$ define

$$
\boldsymbol{\beta}^{\gamma}=\boldsymbol{\beta}+\gamma \mathbf{v}
$$

so that

$$
\mathbf{c}^{\gamma}=\mathbf{X}^{\prime}\left(\mathbf{y}-\mathbf{X} \boldsymbol{\beta}^{\gamma}\right)=\mathbf{c}-\gamma \mathbf{X}^{\prime} \mathbf{X} \mathbf{v}
$$

The conditions that $\boldsymbol{\beta}^{\gamma}$ and $\mathbf{c}^{\gamma}$ need to satisfy are then

- Feasibility: $\boldsymbol{\beta}^{\gamma} \geq 0$.
- Optimality: $\mathbf{c}_{i}^{\gamma}$ maximal for all $i$ such that $\boldsymbol{\beta}_{i}^{\gamma}>0$.
- Increasing: $\sum \boldsymbol{\beta}^{\gamma}>\sum \boldsymbol{\beta}$.


## Defining the search direction

Define $\mathcal{A}=\left\{i: \mathbf{c}_{i}\right.$ maximal $\}$. LARS-Lasso algorithm considers the (unconstrained) search direction $\mathbf{w}$, where $\mathbf{w}_{\mathcal{A}}=\left(\mathbf{X}_{\mathcal{A}}^{\prime} \mathbf{X}_{\mathcal{A}}\right)^{-1} \mathbf{1}$.

From above, the actual search direction should be $\mathbf{v}$ satisfying

- For all $i \in \mathcal{A}$ such that $\boldsymbol{\beta}_{i}=0, \mathbf{v}_{i} \geq 0$.
- For all $i \in \mathcal{A}$ such that $\boldsymbol{\beta}_{i}>0$ or $\mathbf{v}_{i}>0,\left(\mathbf{X}^{\prime} \mathbf{X} \mathbf{v}\right)_{i}=1$.
- For all $i \in \mathcal{A},\left(\mathbf{X}^{\prime} \mathbf{X} \mathbf{v}\right)_{i} \geq 1$.
- For all $i \notin \mathcal{A}, \mathbf{v}_{i}=0$.

These are the KKT conditions for the constrained problem

$$
\min _{\mathbf{v}}\left\|\mathbf{X}\left(\mathbf{v}_{\mathcal{A}}-\mathbf{w}_{\mathcal{A}}\right)\right\| \text { such that } \boldsymbol{\beta}_{i}=0 \Rightarrow \mathbf{v}_{i} \geq 0
$$

where $\mathbf{v}_{i}=0$ for all $i \notin \mathcal{A}$.

## An algorithm for the

```
Let \(\boldsymbol{\beta}=\mathbf{0}\) and \(\mathbf{c}=\mathbf{X}^{\prime} \mathbf{y}\).
while \(\|\mathbf{c}\|>0\)
    \(\mathcal{A}=\left\{i: \mathbf{c}_{i}\right.\) is maximum \(\}\).
```

Choose the search direction $\mathbf{w}_{\mathcal{A}}=\left(\mathbf{X}_{\mathcal{A}}^{\prime} \mathbf{X}_{\mathcal{A}}\right)^{-1} \mathbf{1}$
Find $\mathbf{v}$ minimizing $\left\|\mathbf{X}_{\mathcal{A}}\left(\mathbf{v}_{\mathcal{A}}-\mathbf{w}_{\mathcal{A}}\right)\right\|_{2}$ such that

$$
\mathbf{v}_{i} \geq 0 \text { when } \boldsymbol{\beta}_{i}=0
$$

Move $\boldsymbol{\beta}$ in direction $\mathbf{v}$ until an entry goes negative, OR new variable(s) join the set $\mathcal{A}$ Update $\mathbf{c}=\mathbf{X}^{\prime}(\mathbf{y}-\mathbf{X} \boldsymbol{\beta})$. end


## Application: linear models in phylogenetics

Each edge in the tree corresponds to a split (bipartition) of the objects into two parts. These splits and their weights determine evolutionary distances between the objects:


- y contains the observed distances between objects;
- X indicates which splits/branches separate which pairs;
- $\boldsymbol{\beta}$ is the vector of split/branch weights to be inferred.

$$
\mathbf{y}=\mathbf{X} \boldsymbol{\beta}+\epsilon
$$

## Application: phylogenetic networks

Most collections of splits do not encode a tree, however they can be represented using a split network.


Useful for data exploration since we can depict conflicting signals, and represent the amount of noise*.

## Phylogenetic networks



## From English accents...



## ...to Swedish worms.



## From the origin of modern wheat....



## to the origin of life.



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## Networks and overfitting

With phylogenetic networks we intentionally over-fit the data.
In practice, many variables (splits) are eliminated using NNLS.
A large component of my student Alethea Rea's Ph.D. thesis was devoted to methods for cleaning up the remainder: the Lasso was an obvious choice.

## Numerical issues

Let $n$ be the number of objects. Then

- $\mathbf{X}$ is $\binom{n}{2} \times\binom{ n}{2}$.
- $\mathbf{X}^{\prime} \mathbf{X}$ typically poorly conditioned.
- $\mathbf{X}$ not sparse, but structured, so efficient algorithms for $\mathbf{X v}$, $X^{\prime} v$.
- $\left(\mathbf{X}^{\prime} \mathbf{X}\right)^{-1}$ sparse.


## Numerical issues

$$
\begin{aligned}
& \text { Let } \boldsymbol{\beta}=\mathbf{0} \text { and } \mathbf{c}=\mathbf{X}^{\prime} \mathbf{y} . \\
& \text { while }\|\mathbf{c}\|>0 \\
& \qquad \mathcal{A}=\left\{i: \mathbf{c}_{\boldsymbol{i}} \text { is maximum }\right\} .
\end{aligned}
$$

Choose the search direction $\mathbf{w}_{\mathcal{A}}=\left(\mathbf{X}_{\mathcal{A}}^{\prime} \mathbf{X}_{\mathcal{A}}\right)^{-1} \mathbf{1}$
Find $\mathbf{v}$ minimizing $\left\|\mathbf{X}_{\mathcal{A}}\left(\mathbf{v}_{\mathcal{A}}-\mathbf{w}_{\mathcal{A}}\right)\right\|_{2}$ such that

$$
\mathbf{v}_{i} \geq 0 \text { when } \boldsymbol{\beta}_{i}=0
$$

Move $\boldsymbol{\beta}$ in direction $\mathbf{v}$ until an entry goes negative, OR new variable(s) join the set $\mathcal{A}$
Update $\mathbf{c}=\mathbf{X}^{\prime}(\mathbf{y}-\mathbf{X} \boldsymbol{\beta})$.
end

## Algorithm steps with numerical issues

Let $\boldsymbol{\beta}=\mathbf{0}$ and $\mathbf{c}=\mathbf{X}^{\prime} \mathbf{y}$.
while $\|\mathbf{c}\|>0$
$\mathcal{A}=\left\{i: \mathbf{c}_{i}\right.$ is maximum $\}$.
Choose the search direction $\mathbf{w}_{\mathcal{A}}=\left(\mathbf{X}_{\mathcal{A}}^{\prime} \mathbf{X}_{\mathcal{A}}\right)^{-1} \mathbf{1}$
Find $\mathbf{v}$ minimizing $\left\|\mathbf{X}_{\mathcal{A}}\left(\mathbf{v}_{\mathcal{A}}-\mathbf{w}_{\mathcal{A}}\right)\right\|_{2}$ such that

$$
\mathbf{v}_{i} \geq 0 \text { when } \boldsymbol{\beta}_{i}=0
$$

Move $\boldsymbol{\beta}$ in direction $\mathbf{v}$ until
an entry goes negative, OR
new variable(s) join the set $\mathcal{A}$
Update $\mathbf{c}=\mathbf{X}^{\prime}(\mathbf{y}-\mathbf{X} \boldsymbol{\beta})$.
end

## Strategies

The key computation is the choice of search direction:

$$
\min _{\mathbf{v}}\left\|\mathbf{X}_{\mathcal{A}}\left(\mathbf{v}_{\mathcal{A}}-\mathbf{w}_{\mathcal{A}}\right)\right\|_{2} \text { such that } \boldsymbol{\beta}_{i}=0 \Rightarrow \mathbf{v}_{i} \geq 0
$$

Started with PGCG (thanks to John) but had problems with conditioning of $\left(\mathbf{X}_{\mathcal{A}}^{\prime} \mathbf{X}_{\mathcal{A}}\right)$ and with degeneracy
'Regressed' to an active set method. Made use of the sparseness of $\left(\mathbf{X}^{\prime} \mathbf{X}\right)^{-1}$, PCG and the Woodbury formula to solve sub-problems.

## Simple example: full network

$\longmapsto 0.01$


## Simple example: lasso networks

$\longmapsto 10.0$

DD_PD670
DD-PD6518
DD_PD668
DD-PD638
DD-PD639 DD0̄728

## Simple example: lasso networks

$\longmapsto 0.0010$

## Simple example: lasso networks

$\longmapsto 0.0010$


## Simple example: lasso networks

$\longmapsto 0.01$


## Simple example: lasso networks

$\longmapsto 0.01$


## Simple example: lasso networks



## Simple example: lasso networks

$\longmapsto 0.01$


## Simple example: lasso networks



## Simple example: lasso networks

$\longmapsto 0.01$


## Simple example: lasso networks

$\longmapsto 0.01$


DD_PD668

## Simple example: lasso networks

$\longmapsto 0.01$


## Open problems

(1) Making a choice of $\lambda$.
(2) Weights within the penalty function (adaptive lasso?)
(3) More general error distributions.

## LASSO sampling

What I like most about the LARS and LARS-Lasso algorithm is that you effectively get an estimate for all possible values of $\lambda$ : these are the points on the path $\boldsymbol{\beta}$.

Lasso-LARS sampler for

$$
\pi(\boldsymbol{\beta} \mid \mathbf{y}, \lambda)
$$

would produce a 'nice' function $\boldsymbol{\beta}: \Re \longrightarrow \Re^{n}$ such that for each $\lambda$, $\beta(\lambda)$ has the conditional marginal distribution

$$
\boldsymbol{\beta}(\lambda) \sim \pi(\boldsymbol{\beta} \mid \mathbf{y}, \lambda)
$$

Goal:
(1) Sample $\boldsymbol{\beta}\left(\lambda_{0}\right)$ from $\pi\left(\boldsymbol{\beta} \mid \mathbf{y}, \lambda_{0}\right)$.
(2) Remainder of $\boldsymbol{\beta}(\lambda)$ computed deterministically from $\boldsymbol{\beta}\left(\lambda_{0}\right)$ (e.g. numerically).

We propose a way to 'correct' the LARS-positive lasso algorithm to account for degeneracies.

Motivation was applications to phylogenetic networks, though we are exploring other applications.


